

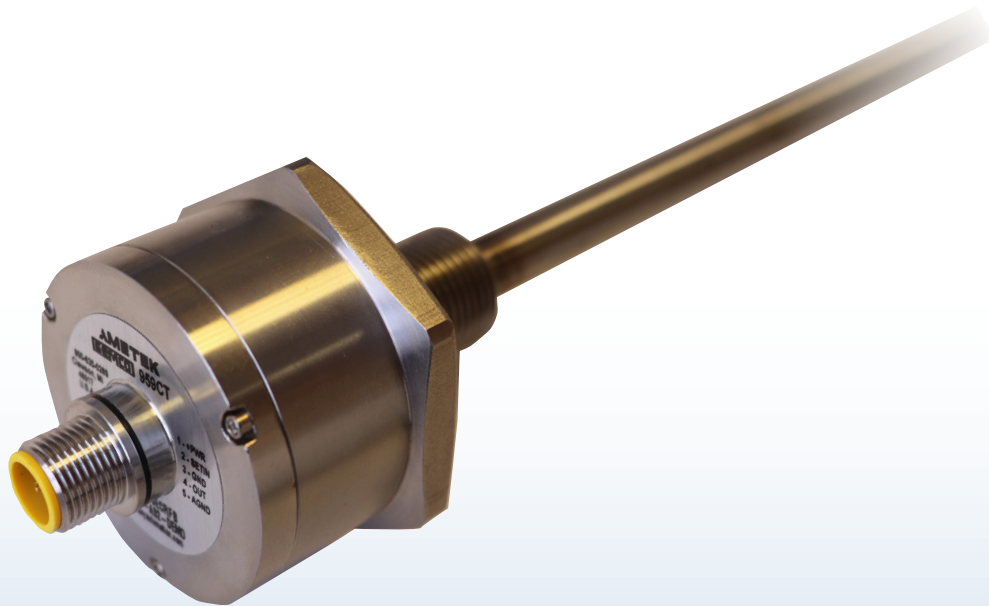


Series 959CT

Linear Displacement Transducer

Installation Manual

959CT



**ABSOLUTE PROCESS CONTROL
KNOW WHERE YOU ARE... REGARDLESS**

Contents

Chapter 1: 959CT Linear Transducer.....	3
1.1 Dimension Drawing.....	4
Chapter 2: Installation.....	5
2.1 Installing in a Hydraulic Cylinder.....	6
Chapter 3: Connections & Wiring.....	7
3.1 Wiring.....	8
3.2 Pinouts and Wiring.....	8
3.3 Features – Automation Gain Control.....	9
3.4 Setting Zero & Span Positions.....	10
Appendix A: Part Numbering.....	11
Appendix B: Specifications.....	12

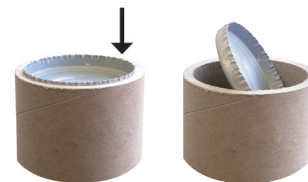
NOTE: Ametek has checked the accuracy of this manual at the time it was approved for printing. This manual may not provide all possible ways of installing and maintaining the LDT. Any errors or additional possibilities to the installation and maintenance of the LDT will be added in subsequent editions. Comments for the improvement of this manual are welcome. Ametek reserves the right to revise and redistribute the entire contents or selected pages of this manual. All rights to the contents of this manual are reserved by Ametek.

Unpacking

Carefully remove the contents of the shipping carton and check each item on the packing slip before destroying the packing materials. Any damage must be reported to the shipping company. If you do not receive all of the parts, contact Ametek at 800-635-0289 (US and Canada) or 248-435-0700 (International).

Most probes are shipped in a Tube. To remove the metal end cap, use a large, flat blade screw driver or a metal rod and tap on the inner edge of the cap until it pivots. Grab the cap and pull it out. Use caution as the edge of the metal cap may be sharp.

If you have an RMA warranty claim, pack the probe in a shipping tube or with stiff reinforcement to prevent the probe from being bent in transit.



Chapter 1: 959CT Linear Transducer Overview

We know today's industrial challenges are extreme, so we designed and built a sensor to meet and exceed these demands, regardless of the application or environment. Innovation, proprietary technology and decades of experience were the key to the development of our 9559CT Linear Displacement Transducer.

The 959CT Series was designed with the hydraulic cylinder market in mind. The 959CT is a rugged, accurate, programmable zero and span, auto-tuning, non-contact linear displacement transducer in a Compact Threaded rod-style package. The Housing is less than 2" in depth, which allows the unit to be installed in applications where traditional Rod style transducers will not fit or in applications where customers are looking to **simplify installation and serviceability** of the sensor. The transducer is made entirely from Stainless Steel and utilizes our field proven Magnetostrictive technology to give absolute analog position feedback, accurate to 0.04% of the programmable sensing distance.

This sensor is built to withstand the most severe environmental conditions and is completely absolute. This means that power loss will not cause the unit to lose position information or require re-zeroing. The non-contact design allows this device to be used in highly repetitive applications without mechanical wear.

The sensor can operate over a wide range of power (8 to 30VDC at 1.6 watts). A variety of different analog outputs with field programmable Zero & Span points are available to meet your needs. The 959CT Series LDT features our auto-tuning capability, which allows the unit to sense a magnet other than the standard ring magnet and adjust its internal signal strength accordingly.

Units can be ordered in English or metric span lengths from 2" to 100" (50mm to 2540mm) and come standard with a 5-pin M12 style connector.

The 959CT units offer a unique diagnostic capability. When the magnet is present and within the programmed range, the unit will output a voltage or current within its selected range (depending on location of magnet). If the magnet moves .050" beyond the programmed Zero or Span points the output will indicate this with a voltage or current outside of the selected range. If the magnet signal is lost the unit will indicate this with a "Loss of Magnet" voltage or current.

See chart below for details on Fault Conditions. All units come 100% calibrated from the factory and do not need to be re-programmed unless desired.

Voltage Output Specified at time of order (i.e. in Part Number)

V0	Range	0 to +10VDC
	Resolution	16 bits (0.0015% of span)
	Fault Condition	Loss of Magnet 10.2V, below or above programmed range -0.1V or 10.1V

V1	Range	+10 to 0VDC
	Resolution	16 bits (0.0015% of span)
	Fault Condition	Loss of Magnet 10.2V, below or above programmed range 10.1V or -0.1V

V2	Range	0 to +5VDC
	Resolution	15 bits (0.0031% of span)
	Fault Condition	Loss of Magnet 5.2V, below or above programmed range -0.1V or 5.1V

V3	Range	+5 to 0VDC
	Resolution	15 bits (0.0031% of span)
	Fault Condition	Loss of Magnet 5.2V, below or above programmed range 5.1V or -0.1V

V4	Range	0.25 to +4.75VDC
	Resolution	~15 bits (0.0034% of span) (14.85 bits)
	Fault Condition	Loss of Magnet 5.2V, below or above programmed range -0.1V or 5.1V

V5	Range	+4.75 to 0.25VDC
	Resolution	~15 bits (0.0034% of span) (14.85 bits)
	Fault Condition	Loss of Magnet 5.2V, below or above programmed range 5.1V or -0.1V

V6	Range	0.5 to +4.5VDC
	Resolution	~15 bits (0.0034% of span) (14.68 bits)
	Fault Condition	Loss of Magnet 5.2V, below or above programmed range -0.1V or 5.1V

V7	Range	+4.5 to 0.5VDC
	Resolution	~15 bits (0.0034% of span) (14.68 bits)
	Fault Condition	Loss of Magnet 5.2V, below or above programmed range 5.1V or -0.1V

Current Output Specified at time of order (i.e. in Part Number)

C2	Range	20 to 4mA
	Resolution	15.7 bits, calibrated for 3.5-21mA (0 - 21mA, 16 bits)
	Fault Condition	Loss of Magnet 3.8mA, below or above programmed range 20.1mA or 3.9mA

C4	Range	4 to 20mA
	Resolution	15.7 bits, calibrated for 3.5-21mA (0 - 21mA, 16 bits)
	Fault Condition	Loss of Magnet 3.8mA, below or above programmed range 3.9mA or 20.1mA

All units can easily be changed in the field for reverse operation. See section 3.4 Setting Zero & Span Positions.

1.1: Dimension Drawing 959CT

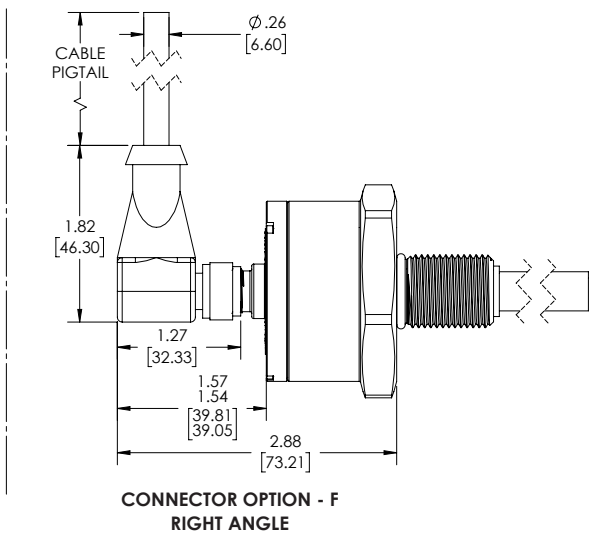
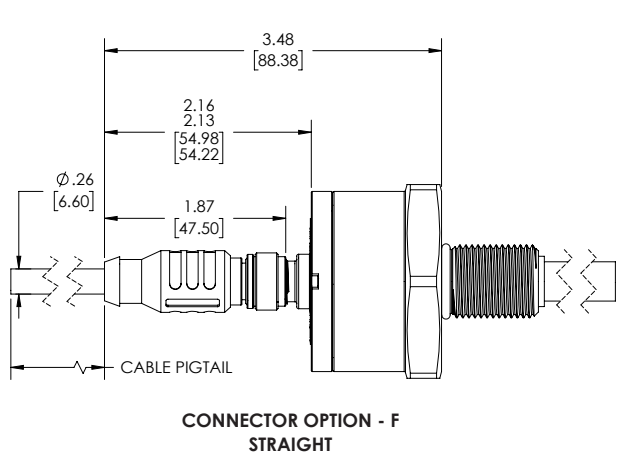
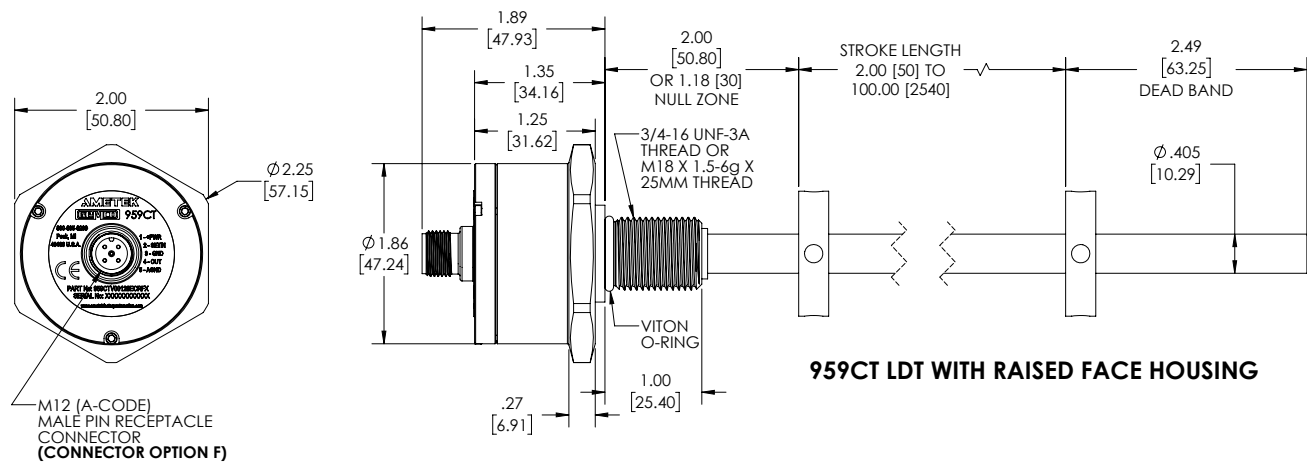
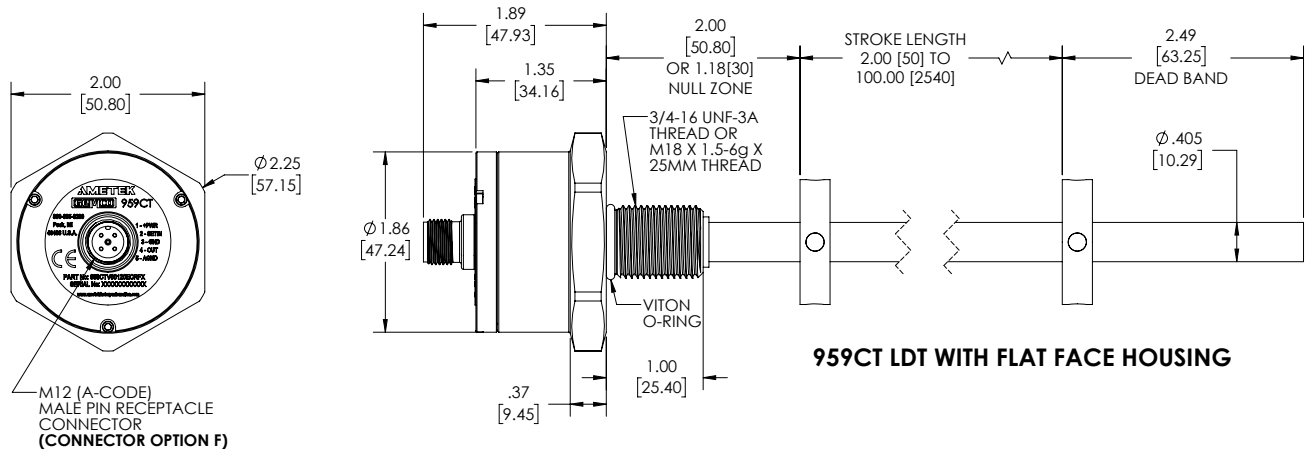


Figure 1-1: 959CT – Dimension drawing (PD-0129100)

Chapter 2: Installing the LDT

The 959CT Housing is designed with the hydraulic cylinder market in mind. The hydraulic cylinder must be prepped for a Rod Style Linear Transducer.

2.1: Installing the LDT in a Hydraulic Cylinder

Before installing an LDT in a hydraulic cylinder, note the following considerations. Items discussed in this section are found in Figures 2-1 and 2-2.

- There are 3 different magnet styles offered (see accessories page). When the magnet is installed in a ferrous material it is necessary to add a non-ferrous spacer between the magnet and piston. Non-ferrous materials, such as brass, copper, aluminum, non-magnetic stainless steel, or plastics, can be in direct contact with the magnet assembly and rod end without producing any adverse results. The magnet should not be closer than 1.18" (30mm) from the base of the LDT's hex head when the piston rod is fully retracted. In instances where space restraints exist, it may be required to countersink the magnet into the piston rod. Three magnets are available for mounting to the piston: the standard 1.29" in diameter (P/N SD0400800) four-hole magnet, the 1.0" cylinder magnet (P/N SD0410300) and our 17.4mm (04-588105) magnet. The SD0410300 and 04-588105 magnets are designed exclusively for countersunk mounting applications. These magnets must be secured with a snap ring.
- An O-ring is provided at the base of the LDT's mounting hex for pressure sealing. The O-ring seal was designed to meet Mil-Std-MS33656. Refer to SAE J514 or SAE J1926/1 for machining of mating surfaces.
- A chamfered rod bushing in front of the magnet may be required. It is recommended that a chamfered rod bushing be used with LDTs having a rod 60.0" or longer. This bushing will help prevent wear on the magnet assembly (wear occurs as the piston retracts from extended lengths). This rod bushing should be manufactured from a high wear polymer, such as Teflon®.
- It is recommended the bore for the cylinder piston rod have an inside diameter of at least 0.50". The LDT rod has an outside diameter of 0.405". Use standard practices for machining and mounting these components. Consult the cylinder manufacturer for details on applicable SAE or military specifications.

It may be necessary to perform machining and mounting operations on the hydraulic cylinder before installing the LDT. Consult the information and specifications provided by the cylinder manufacturer before beginning the following steps:

1. Unscrew the LDT's jam nut from the threads protruding from the head assembly.
2. Position the non-ferrous spacer against the piston face, followed by the magnet, and then the chamfered rod bushing if the LDT's rod is 60.0" or longer in length.
3. Insert non-ferrous screws through the chamfered rod bushing (if used), magnet, and non-ferrous spacer. Secure items by tightening screws.
4. If the leading edge of the magnet will come closer than 1.18" (30mm) from the base of the LDT's hex head when the piston rod is fully retracted, it will be necessary to counterbore the magnet assembly into the piston rod. Refer to LDT part number to determine if the 1.18" (30mm) or 2.0" (50.4mm) Null Band was ordered.
5. Insert the LDT's rod into the hole of the hydraulic cylinder's mounting bracket. The protective Plug may need to be removed from the hydraulic cylinder before inserting the LDT. The end cap should contain a 3/4-16 UNF-2B threaded hole (M18 x 1.5 for metric units). Screw the LDT into this hole and tighten using the 2.0" flats across the LDT's hex base.

Chapter 3: Connections and Wiring

Once the LDT has been installed, wiring connections can be made. All units come standard with a 5-pin M12 (A-Code) connector. See Figure 3-2.

Once the LDT has been installed, wiring connections can be made. It is recommended to use an industry standard 5-pin 12mm Euro style cordset with a shield tied to the coupling nut. Connect the cable's shield to the controller system Ground. Always observe proper grounding techniques and isolate high voltage (i.e. 120/240VAC) from low voltage (i.e. 24 VDC cables).



WARNING: Do not route the LDT cable near high voltage sources.

Warning: Do not use molded cordsets with LEDs!

It is preferable that the cable between the LDT and the interface device be one continuous run. If you are using a junction box, it is recommended that the splice junction box be free of AC and/or DC transient-producing lines. The shield should be carried through the splice and terminated at the interface device end.

NOTE: When grounding the LDT, a single earth ground should be connected to the Power Supply Common (circuit ground). The LDT Power Supply Common should be connected to the Power Supply Common (-) terminal. The LDT power supply (+VDC) should be connected to the power supply positive terminal (+). The LDT cable shield should be tied to earth ground at the power supply. The LDT analog common should not be connected to earth ground and should be used for connection to interface devices only.

The 959CT offers up to 16-Bits of resolution. If the programming option was selected it is fully programmable over the entire active stroke length. Refer to part number grid to see if this option was selected. Keep in mind that there is a 1.18" (30mm) or a 2.0" (50.8mm) Null Zone at the connector end of the LDT and a 2.49" (63.25mm) Dead Band at the other end of the LDT that the magnet must stay out of at all times. All units come fully programmed from the factory and do not require re-programming unless desired. Refer to part number on label for Null dimensions.

The analog output is referenced to the analog common terminal and should not be referenced to any of the other common terminals. For wiring, see Figure 3-1. For programming Zero and Span, See Section 3.4.

3.1: Wiring

Figure 3-1 shows two common methods for wiring the 959CT to a customer supplied interface device, such as a PLC or motion controller. The two different methods are commonly referred to as Single Ended Input and Differential Input. Differential Input is the preferred wiring method.

With the Differential Input, the Analog Common wire is connected to the customer supplied input device and the Power Supply Common is wired separately to the customers supplied power source. When wired using the Differential method, the electrical noise and voltage offset errors produced by the currents running through the Power Supply Common are eliminated. The Power Supply Common and Analog Common are internally connected inside of the 959CT LDT.

Series 959CT Linear Transducer

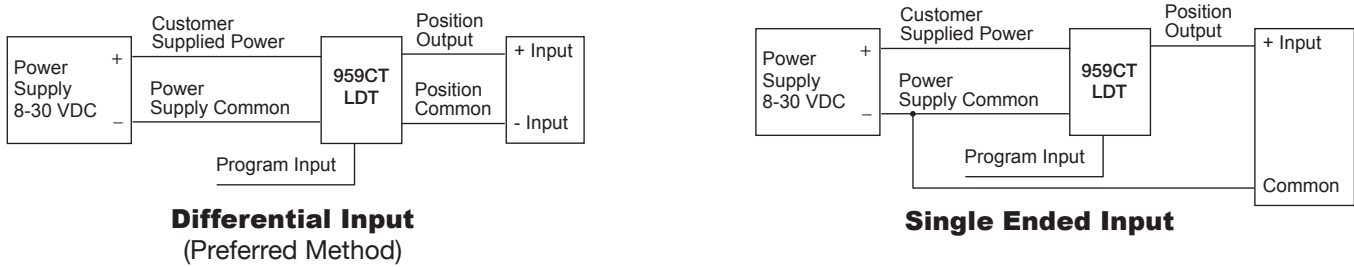
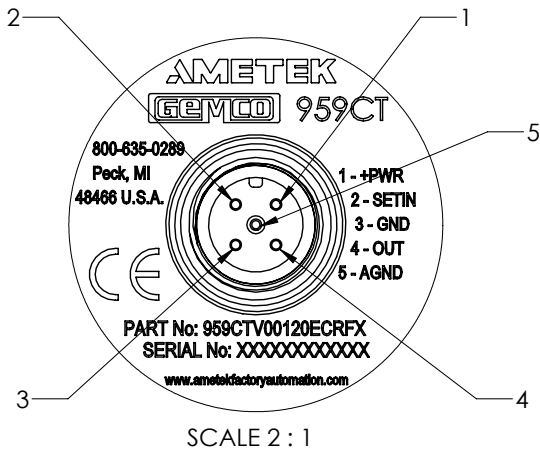


Figure 3-1: Wiring – Single Ended vs. Differential

The 959CT- with the 4-20mA option is current sourcing, which allows the current to flow from the LDT into the user's equipment.

3.2: Pinouts and Wiring

All units come standard with a 5-Pin M12 (A-Code) connector.



CONNECTOR OPTION - F

PIN NUMBER	DESCRIPTION	WIRE COLOR ON CABLE
1	POWER SUPPLY	BROWN
2	PROGRAMMING INPUT	WHITE
3	POWER SUPPLY COMMON	BLUE
4	ANALOG OUTPUT	BLACK
5	ANALOG COMMON	GRAY

Cable Specifications				
Cable Type	Gauge	Jacket	Temp	Bend Radius
Connector Option F	22	PVC	-40° to 105°C	Fixed Applications 1.3" Moving Applications 2.6"

3.3: Features

Automatic Gain Control

The Automatic Gain Control feature will automatically search and find the magnet on power up and adjust its internal signal strength to the optimum setting. It is important that the magnet be installed on the rod and within the active sensing range when power is applied to the LDT. If power is applied without a magnet on the LDT, the LDT will go into a fault condition and transmit a voltage or current outside of the programmed range. See Chapter 1: 959CT Overview, for list of fault conditions and outputs. To correct this, turn power off and place magnet within the active stroke area, re-apply power.

3.4: Setting Zero & Span Positions

As an option the 959CT can be ordered with Programmable Zero & Span positions. See page 11, Part Numbering to see if this option was selected. Note: If option “P” or “B” was not selected in part number configuration, the unit is non-programmable and cannot be rescaled.

All units come fully programmed from the factory and do not require re-programming unless desired. All units are 100% absolute and will not lose programmed parameters on power loss. The Zero and Span points can be programmed in any order and anywhere within the LDT’s active sensor area.

NOTE 1: Zero or Span can be adjusted individually without setting the other.

NOTE 2: Zero = 0V on 0-10 VDC, 0V on 0-5 VDC, .25 on .25-4.75 VDC, .5 on .5-4.5 VDC units and 4mA on 4-20mA units.

There is a timing sequence that is used to unlock the probe for programming. This is to ensure that the Zero or Span positions cannot be accidentally re-programmed by someone in the field.

Before programming the Zero or Span, the program input must be connected to the Power Supply Common for a minimum of 2 seconds and no more than 6 seconds, then released for 1 second. The LTD programming sequence is now unlocked and will remain an unlocked unit until either the Zero or Span is programmed or the 10 second programming sequence times out. During the unlock mode either the Zero or Span can be programmed by momentarily connecting the Program Input to either the Power Supply Common or Power Supply +VDC.

NOTE: The LDT must be unlocked to program the Zero and unlocked again to program the Span. Once either the Zero or Span is programmed the LDT will go back into the locked mode.



WARNING: During normal operation, electrically insulate the Program wire to prevent accidental setting of Span.

Manual Setting of Zero & Span

To set the Zero and Span position, follow these steps:

1. Apply power to the LDT.
2. Place magnet assembly where Zero is to be located, but within the active region of the probe.
3. Short the Program Input pin to the Power Supply Common for 4 seconds. Remove the short for 1 second. Within 5 seconds, short the Programming Input pin to the Power Supply Common. This completes the Zero programming process.
4. Place magnet assembly where Span is to be located, but within the active region of the probe.
5. Short the Program Input pin to the Power Supply Common for 4 seconds. Remove the short for 1 second. Within 5 seconds, short the Programming Input pin to the Power Supply +VDC.

This completes the programming process.

NOTE: The LDT must be unlocked to program the Zero and unlocked again to program the Span. Once either the Zero or Span is programmed the LDT will go back into the locked mode.



WARNING: During normal operation, electrically insulate the Program wire to prevent accidental setting of Span.

Optional Remote Tester & Programmer

The battery-operated remote tester / programmer is available in either a voltage or current model. P/N SD0528810 is designed for voltage units while SD0528811 is for current units. Both units are designed to work with connector option F only. These units are typically used to demonstrate the functionality of the LDT in the field, however, they can be used as a handy troubleshooting / programming device.

1. Attach the 5 pin Euro connector to the LDT.
2. Push the toggle switch to the ON position to power the LDT.
3. Place magnet assembly where Zero is to be located, but within the active region of the probe.
4. Push the black Zero button for 4 seconds, release for 1 second. Within 5 seconds, push the Zero button again. This completes the Zero programming process.
5. Place magnet assembly where Span is to be located, but within the active region of the probe.
6. Push the black Zero button for 4 seconds, release for 1 second. Within 5 seconds, push the Span button. **NOTE:** This time the Span button is pushed for the final programming step.

This completes the programming process.



Optional In-Line Programmer

The 955-1409 is a remote programmer that can help simplify the programming process. The programmer is a portable device that can be temporarily or permanently installed in series with the 959CT with connector option F.

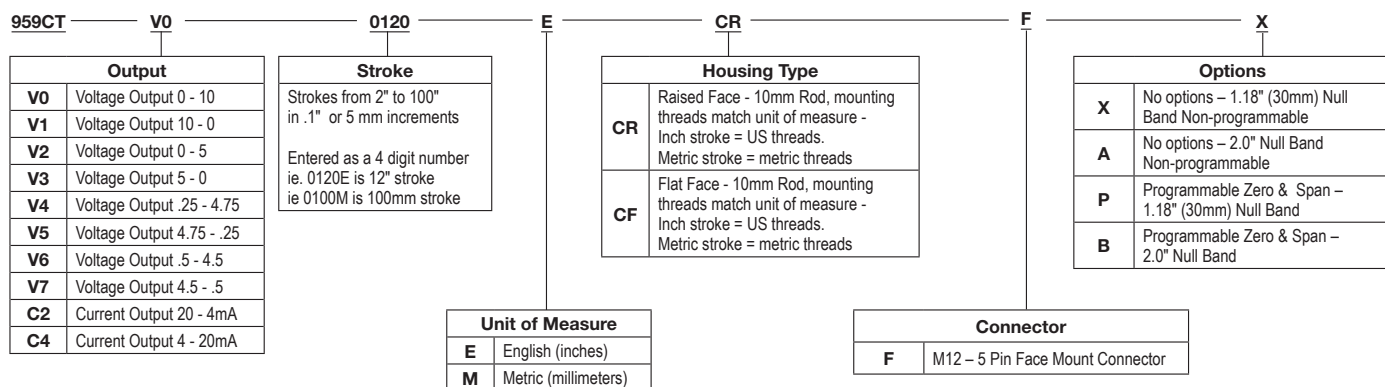
1. Remove the 5 pin cordset to the LDT.
2. Attach the existing cordset to the 955-1409 programmer.
3. Attach the other end to the LDT.
4. Apply power to the LDT.
5. Place magnet assembly where Zero is to be located, but within the active region of the probe.
6. Push the Zero button for 4 seconds. Release the button for 1 second. Within 5 seconds, push the Zero button again.
7. Place magnet assembly where Span is to be located, but within the active region of the probe.
8. Push the Zero button for 4 seconds. Release the Zero button for 1 second. Within 5 seconds, push the Span button.



This completes the programming process.

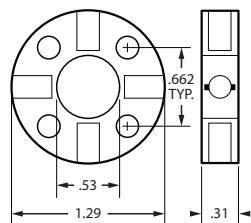
Appendix A: Part Numbering

The 959CT Series LDT is available with a variety of analog outputs and mounting configurations. The numbering scheme below will break down all available options. The “Unit of Measure” field will allow you to select either inch or millimeter threads as well as stroke lengths.

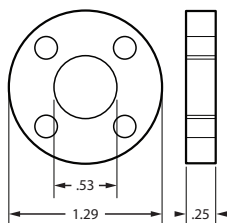


Accessories – Magnets and Cables

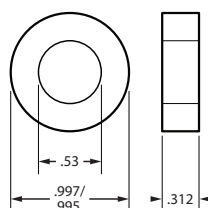
There are 3 magnet choices available for the 959CT Series. Magnets and Magnet spacers must be ordered as separate line items.



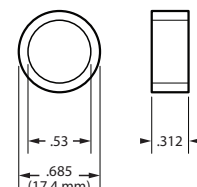
Standard 4 Hole Magnet
P/N: SD0400800



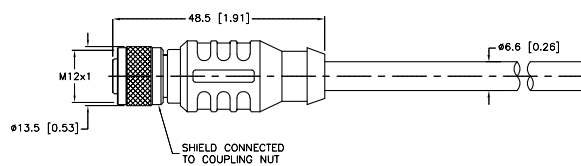
Non-Ferrous Spacer for
4 Hole Magnet
P/N: M0822400



1" Cylinder Magnet
P/N: SD0410300

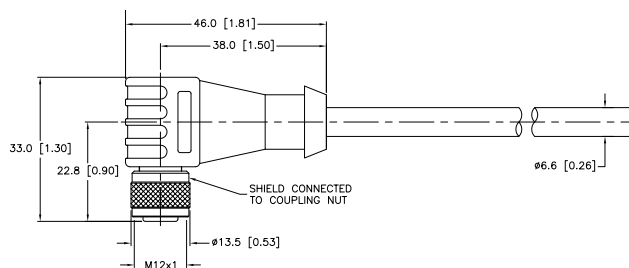


17.4 mm Cylinder Magnet
P/N: 04588105



Straight Connector

Cable M12-A Straight to flying leads - Shielded	Part #
PVC Jacket - Nickel Plated Brass Coupling Nut - 6 ft long	949019L6
PVC Jacket - Nickel Plated Brass Coupling Nut - 12 ft long	949019L12
PVC Jacket - Stainless Steel Coupling Nut - 6 ft long	949047L6
PVC Jacket - Stainless Steel Coupling Nut - 12 ft long	949047L12



Right Angle Connector

Cable M12-A Right Angle to flying leads - Shielded	Part #
PVC Jacket - Nickel Plated Brass Coupling Nut - 6 ft long	949020L6
PVC Jacket - Nickel Plated Brass Coupling Nut - 12 ft long	949020L12
PVC Jacket - Stainless Steel Coupling Nut - 6 ft long	949048L6
PVC Jacket - Stainless Steel Coupling Nut - 12 ft long	949048L12

Series 959CT Linear Transducer

Appendix B: Specifications

General Specifications	
Displacement	2" to 100" (50mm to 2540mm) in .1" or 5mm increments

Performance Specifications - Measurement	
Linearity	+/-0.04% of Span or +/-0.008", whichever is greater
Hysteresis	0.001" maximum
Repeatability	Equal to Resolution of output signal, +/-0.01% of Span or 0.001", whichever is greater
Update Time	0.5 ms minimum, proportional to length of LDT - not to exceed 4ms

Null & Dead Bands	
Null	1.18" (30mm) or 2.0" (50.8mm) – Part number dependent
Dead	2.49" (63.25mm) from end of rod

Mechanical Specifications - Housing	
Material - Housing	Stainless Steel 1.4404 / AISI 316
Diameter	2.25" (57.15mm)
Length (width)	1.89" (47.93mm)
Guide Tube Material	Stainless Steel 1.4404 / AISI 316/316L
Diameter - Guide Tube	10mm (10.29mm actual)
Guide Tube Pressure	
Continuous	5,076 PSI (350 bar)
Spike	10,000 PSI (689 bar)

Temperature	
Head - Electronics	-40°C to + 85°C
Guide Tube	-40°C to + 105°C
Storage	-40°C to + 105°C

Shock & Vibration	
Shock	100G, single hit (per IEC 60068-2-27)
Vibration	20G, 10Hz - 2kHz (per IEC 60068-2-6)

Ingress Protection	
Protection level	IP68 (per EN 60529)

Electrical Specifications	
Power Consumption	1.6 Watt maximum (50mA @ 24VDC typical)
Input Voltage	8 to 30VDC

Protection	
Polarity	Reverse polarity protected
Overvoltage	Transient overvoltage protection to +33VDC

Output Resolution	
0 to 10VDC	16 bits (0.0015% of span)
0 to 5VDC	15 bits (0.0031% of span)
0.25 to +4.75VDC	~15 bits (0.0034% of span) (14.85 bits)
0.5 to +4.5VDC	~15 bits (0.0034% of span) (14.85 bits)
4 to 20mA	15.7 bits, calibrated for 3.5-21mA (0 - 21mA, 16 bits)

Output Loading	
Voltage	2k Ω minimum
Current	500 Ω maximum

Connection Options	
5 Pin - M12	5 pin -A-Code

Isolation	
Housing to any signal	500V

Approvals	
CE (Electromagnetic Compatibility)	2014/30/EU - When installed in grounded metal housing
RoHS 2	2011/65/EU
Electromagnetic compatibility - Part 6-4: Generic standards – Emission standards for industrial environments	EN61000-6-4
Electromagnetic compatibility (EMC) - Part 6-2: Generic standards – Immunity for industrial environments	EN61000-6-2
Agricultural and forestry machinery	ISO 14982:1998
Road vehicles - electrical disturbances from narrowband radiated electromagnetic energy — Part 5: Stripline	ISO 11452-5
Road vehicles - Electrical disturbances from conduction and coupling	ISO 7637-1/2/3
Earthmoving Machinery	ISO 13766
Industrial Trucks	EN 12895
Railway Applications	EN 50121-3-2

953 VMAX LDT

- Shock resistant to 1000Gs
- Vibration resistant to 30Gs
- Analog outputs, 0-10 VDC, +/-10 VDC, 0-5 VDC, +/-5 VDC, 4-20mA
- Digital output Start/Stop, Control Pulse, and Variable Pulse (PWM)
- SSI (Synchronous Serial Interface) 24, 25, or 26 Bit, Binary or Gray Code, Synchronous or Asynchronous Mode
- Removable cartridge
- IP68 rating
- Stroke length to 300"
- Input power range is 7 to 30 VDC
- Programmable zero and span
- Diagnostic Tri-Color LED



958A Embedded LDT

- Embedded Style LDT
- Shock resistant to 1,000 Gs
- Vibration resistant to 30 Gs
- Strokes from 2" to 100"
- Analog Outputs, 0 to 10VDC, 0.25 to 4.75VDC, 0.5 to 4.5VDC or 4-20mA
- 16-bit resolution
- Multiple connector options—M12 – 5 pin, Integral cables, bare leads
- IP68
- Programmable Zero & Span
- Diagnostics



Other Products



LINEAR DISPLACEMENT TRANSDUCERS

PLC INTERFACE PRODUCTS

ROTARY POSITION PRODUCTS

PROGRAMMABLE LIMIT SWITCHES

EXTREME DUTY CABLE REEL PRODUCTS

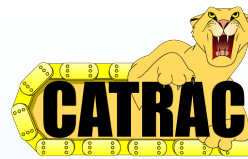
ROTARY LIMIT SWITCHES

RESOLVERS

MILL DUTY ENCLOSURES

ULTRA HIGH SPEED PLS

SAFETY PRODUCTS



MADE IN AMERICA

Copyright 2020 by AMETEK FACTORY AUTOMATION. All Rights Reserved. Made in the USA.

6380 Brockway Rd, Peck, Michigan 48466

Phone: 248-435-0700 Toll Free: 800-635-0289

Email: apt.sales@ametek.com

Web: www.ametekfactoryautomation.com

AMETEK
FACTORY AUTOMATION

959CT.M0R
09.20.Z448